



FLASH FLOODS AND PLUVIAL FLOODING



ISPRA
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REGIONE AUTONOMA
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MINISTERO DELL'AMBIENTE
E DELLA TUTELA DEL TERRITORIO E DEL MARE

Working Group F Thematic Workshop

DETERMINING FLOOD HAZARD PATTERNS THROUGH A COMBINED STOCHASTIC- DETERMINISTIC APPROACH

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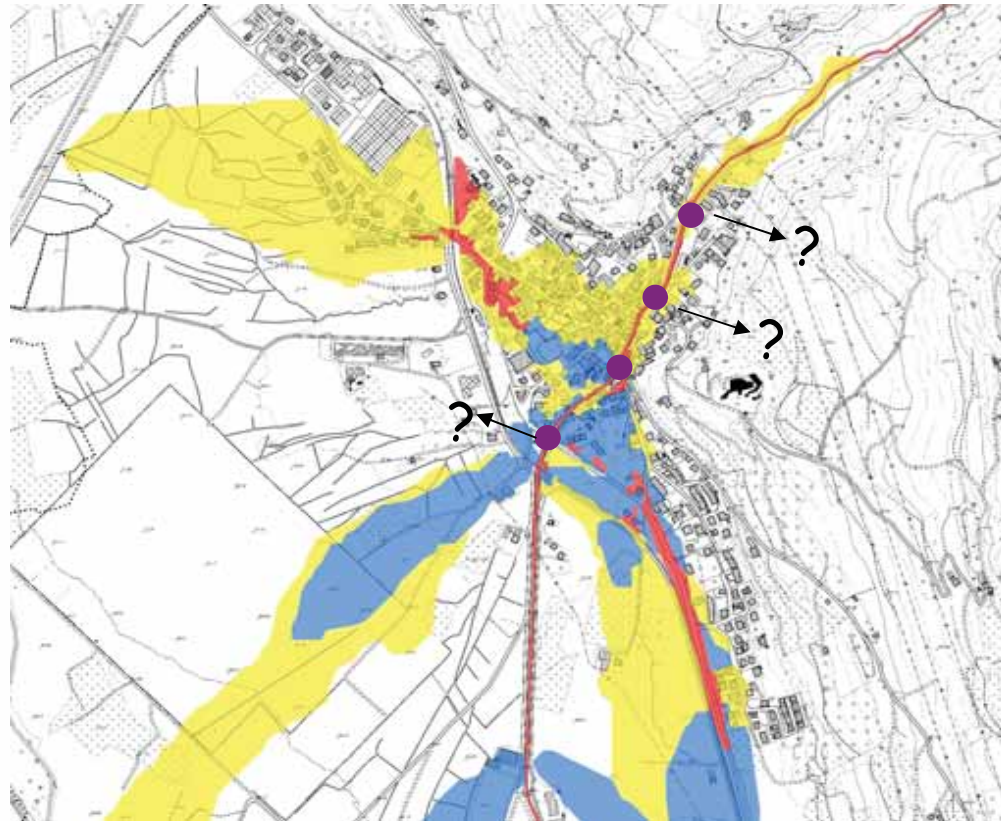
³ Obrist & Partner Engineering



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HOW RELIABLE ARE HAZARD MAPS ?



Example:
Schluderns (Prov.
BZ, Italy)



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FLOOD HAZARD IS USUALLY ASSIGNED BASED ON WATER DEPTH AND VELOCITY (PROCESS INTENSITY) FOR GIVEN RECURRENCE INTERVALS



DEPTH AND VELOCITY ARE USUALLY ESTIMATED RUNNING DETERMINISTIC HYDRODYNAMIC MODELS ON A DTM (usually fixed, no morphodynamic changes)



BUT DO FLOOD EVENTS EXHIBIT A DETERMINISTIC BEHAVIOUR ?



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MORPHODYNAMIC PROCESSES OCCURING DURING FLOODS



Aggradation →



← Incision

Vertical changes up to 10 m
in mountain streams !



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MORPHODYNAMIC PROCESSES OCCURING DURING FLOODS

Avulsion





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STOCHASTIC PROCESSES OCCURING DURING FLOODS



Levee failure

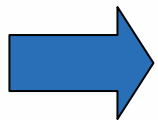


Bridge obstruction



MORPHODYNAMIC AND STOCHASTIC PROCESSES MAY RENDER DETERMINISTIC HAZARDS MAPS WRONG !

- Directing flood flows to routes not predicted by numerical models (not including the stochastic description of levee failure, bridge obstruction, morphodynamic changes)
- Changing flow depth / velocity on areas where flooding was predicted by numerical models



Magnitude-frequency relationships of inundation altered !



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HOW TO COPE WITH SUCH PROCESSES ?

- Potentially, channel changes during flood events could be accounted for by using morphodynamic models (but with large uncertainties, especially in mountain rivers)
- But how could we include stochastic process stemming from wood transport and/or geotechnical issues in the hazard mapping ?



PROPOSAL OF A NEW APPROACH

- Within a “response system” (e.g. alluvial fan, floodplain):



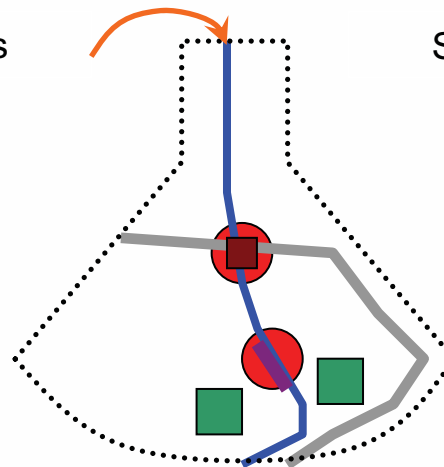


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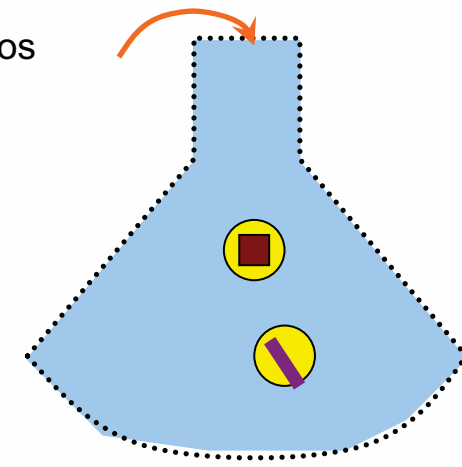
Response System

System loading scenarios



Abstracted Response System

System loading scenarios



Legend:

- | | | | | | |
|--|-----------------|--|------------------------|--|----------------------|
| | System boundary | | Residential buildings | | Stochastic domain |
| | channel | | road | | Deterministic domain |
| | bridge | | Critical configuration | | |
| | levee | | | | |

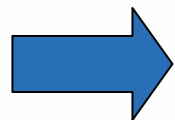


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- Each stochastic node, depending on the intensity of the hazard process, can feature only a finite (and small) set of possible states
- A node undergoes a variation of its state through transitions, whose number is also finite
- A matrix describing the possible transitions among states for different process intensity can be written for each node



The probability for each transition must be provided by experts



Based either on empirical relationships and/or
on subjective probability theory



An introductory example:

A response system with only one stochastic domain:

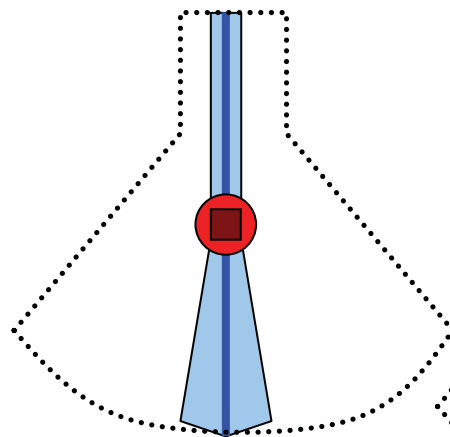
alluvial fan (one single paved channel and one bridge cross section as a stochastic domain)

Case 1:

stochastic domain)

Case 3:

$$S(-obstr) \xrightarrow{tr} S(-obstr)$$

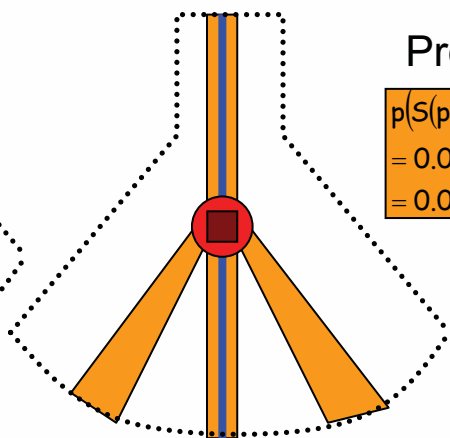


Probability Case 1:

$$p(S(-obstr) | S(-obstr) \wedge I_{P_t}) = 0.01 \cdot 0.4 = 0.004$$

Case 2:

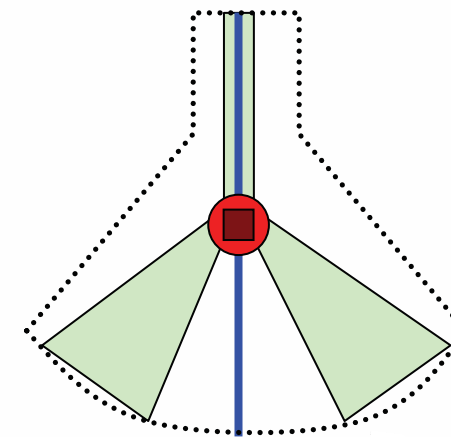
$$S(-obstr) \xrightarrow{tr} S(\text{partially obstr})$$



Probability Case 2:

$$p(S(\text{partially obstr}) | S(-obstr) \wedge I_{P_t}) = 0.01 \cdot 0.5 = 0.005$$

$$S(-obstr) \xrightarrow{tr} S(\text{totally obstr})$$



Probability Case 3:

$$p(S(\text{totally obstr}) | S(-obstr) \wedge I_{P_t}) = 0.01 \cdot 0.1 = 0.001$$

$$\sum p(S_j | S_i \wedge I_{P_t}) = p_I = 0.01$$

40% 25%

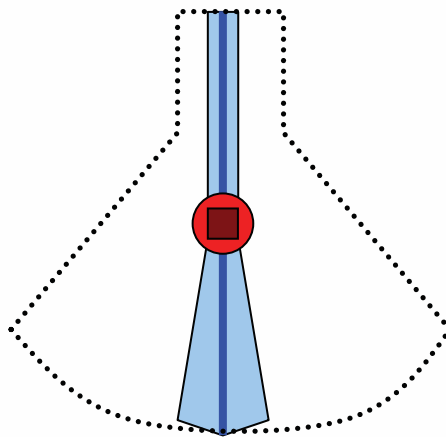


An introductory example:

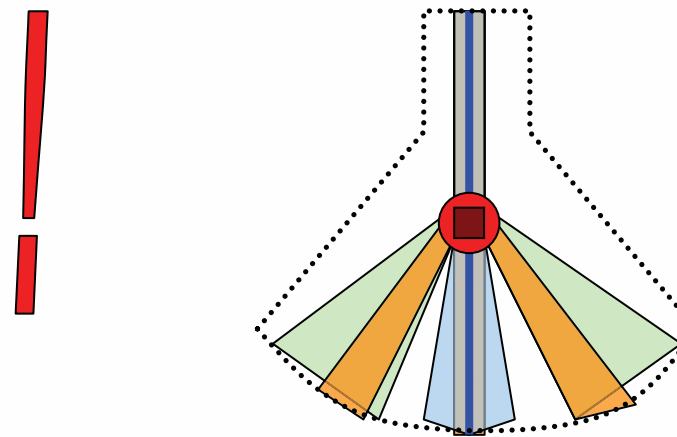
A response system with only one stochastic domain:

➔ alluvial fan (one single channel and one bridge)

Single Scenario normally considered in hazard mapping



Overlapping Scenarios that should be considered in hazard mapping





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The general case:

- A response system with n stochastic domains
- n matrices describing the possible transitions among domain states for different process intensities are needed

	$(S_1 \xrightarrow{tr} S_1)$	$(S_i \xrightarrow{tr} S_j)$	$(S_n \xrightarrow{tr} S_n)$
I_1	$p(S_1 (S_1 \wedge I_1))$	$p(S_j (S_i \wedge I_1))$	$p(S_n (S_n \wedge I_1))$
\vdots	\vdots	\vdots	\vdots
I_N	$p(S_1 (S_1 \wedge I_N))$	$p(S_j (S_i \wedge I_N))$	$p(S_n (S_n \wedge I_N))$

∇ STOCHASTIC DOMAIN

- Depending on the local process intensities and the “response behaviour”, the probabilistic state transition for each stochastic domain is selected

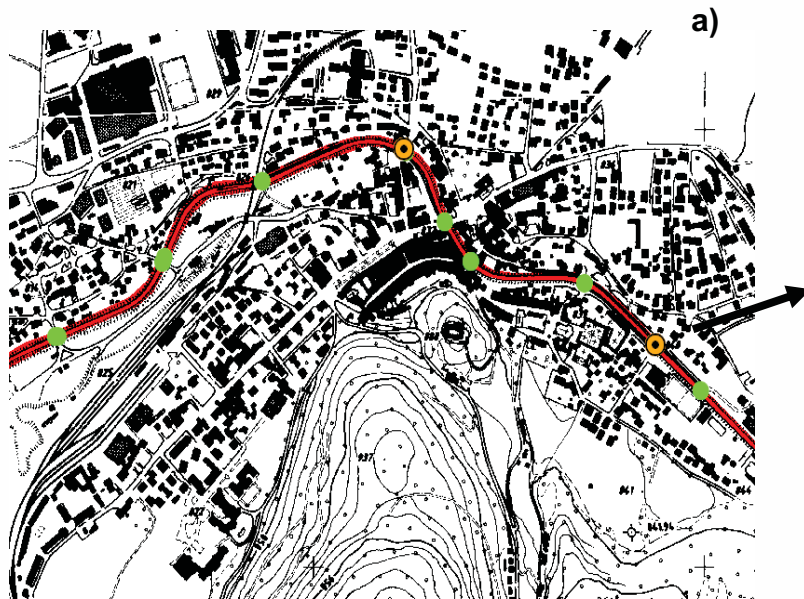
Test case: the Rienz in Bruneck



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Test case: The Rienz River in Brunico



High wood load expected
for RI > 30 - 50 yr



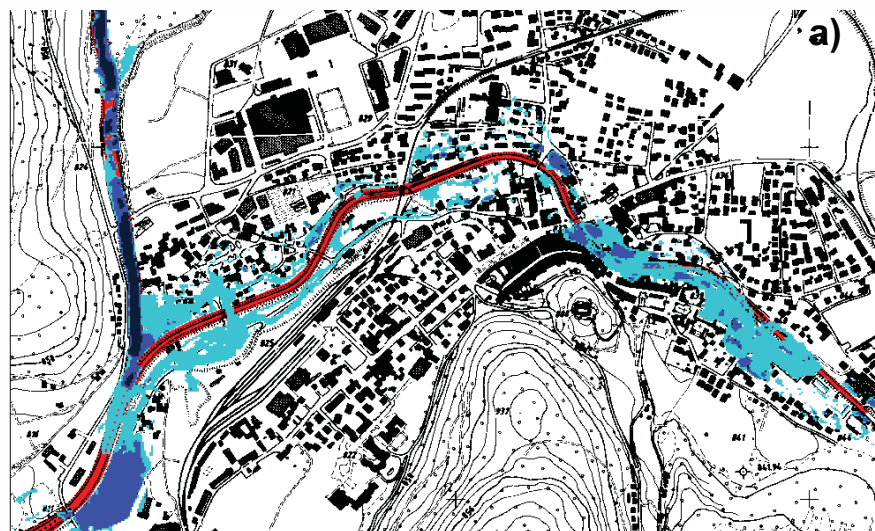
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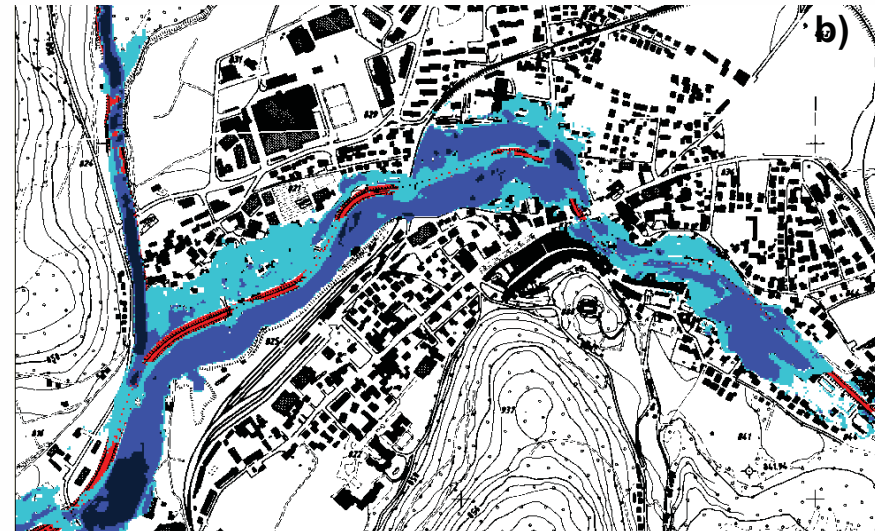
Test case (in progress): the Rienz River in Brunico

- Inundation maps at the flood peak (inflow hydrograph R.I. 100 yr) for a subset of the possible propagation scenarios for the Rienz in Bruneck

bridges not clogged



both critical bridges clogged



Test case: the Rienz in Bruneck



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CONCLUSIONS

- Flood hazard mapping procedures carried out without taking into account different scenarios can result in highly erroneous evaluations.
- A nested approach entailing deterministic simulations as well as stochastic evaluation is thus advocated for in order to achieve a more reliable determination of flood risks.
- The necessary system representation step “forces” the analyst to consider a broad set of possible system behaviors.
- Knowledge resulting from past event documentation should be appropriately integrated into hazard assessment.
- Benefits for the whole risk governance cycle (risk assessment, insurance policy, intervention planning).



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